

Local Evidence and Diversity in Minipublics

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Novel mechanism for citizen participation in public policymaking

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- Lay citizens can access local evidence: privileged insight into how the policy is likely to impact them
- But citizenry-wide deliberation on policies is infeasible
 - rational ignorance (Schumpeter (1950), Downs (1957), Martinelli (2006))
 - minipublics as a small group of "trusted information proxies"

Novel mechanism for citizen participation in public policymaking

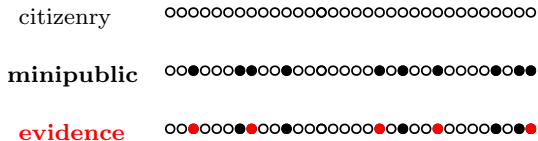
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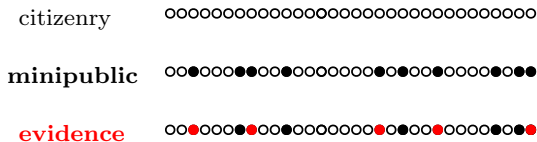
Which social groups ought to be represented in a minipublic?

Evidence production in minipublics



How to select a minipublic from a large citizenry if:

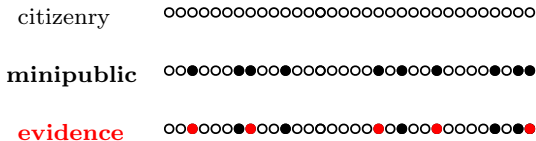
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- ▶ each citizen chooses whether to produce his **local evidence**
- ▶ local evidence is **correlated** across citizens

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- ▶ local evidence is **correlated** across citizens
- ▶ policymaker makes **policy decision** based on the produced evidence
- ▶ minipublic faces **uncertainty** about the eventual decision threshold

Citizens' Climate Convention in France

- Minipublics recently used across Europe to address climate policy
- CCC: 150 ordinary citizens representative of the French society
 - targeted by gender, age, education, occupation, residence, and geographical area
 - other criteria such as ethnicity or attitudes on climate change not included
- October 2019 - June 2020
- Tasked with advising Macron on France's climate strategy



A plenary session of the Citizen convention for the climate, 20 March 2020. © RFI/Agnès Rougier

Citizens' Climate Convention in France

- Political uncertainty accompanied CCC throughout its proceedings
- Initially Macron pledged to forward recommendations **“without filter”** to either parliament or a referendum
- Ultimately 10% of CCC’s recommendations accepted by the government without modification, 37% modified or watered down, and 53% rejected

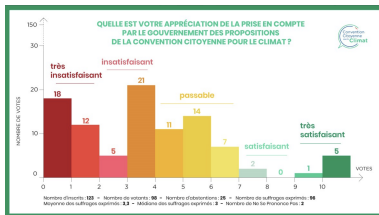


Figure 1: Convention Citoyenne Pour Le Climat, Session 8 (February 26-28 2021)

Concerns about political uncertainty and limited impact spilled over to Scotland’s Climate Assembly and the UK Climate Assembly

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1. **Evidence production:**

How does political uncertainty affect citizens' incentives to contribute local evidence in a minipublic?

2. **Minipublic design:**

To what degree is the optimal minipublic representative of the citizenry?

Baseline model

Policymaker's problem

Optimal minipublic

Minipublic size

Minipublic composition

Comparative statics

Discussion

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Players

- A single **policymaker**
- Unit mass of **citizens** $i \in [0, 1]$
- A **minipublic** consists of distinct citizens $\mathbf{m} = \{i_1, \dots, i_k\}$ ordered as

$$0 \leq i_1 < \dots < i_k \leq 1$$

- A minipublic can accommodate at most n citizens (**minipublic capacity**)
- \mathcal{M}_n is the set of all minipublics of size at most $n \geq 0$

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 - e.g., $\beta(i)$ as the **realized local impact** of the policy for demographic $i \in [0, 1]$ and B as the **average local impact** across all demographics

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- $\beta(\mathbf{m}) := (\beta(i_1), \dots, \beta(i_n))$ local evidence available to minipublic \mathbf{m}
- For any minipublic, B and $\beta(\mathbf{m})$ follow a multivariate Gaussian distribution

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- For any minipublic, B and $\beta(\mathbf{m})$ follow a multivariate Gaussian distribution
- **Post-minipublic value** $B_{\mathbf{m}} = \mathbb{E}[B \mid \mathbf{m}, \beta(\mathbf{m})]$ is distributed according to

$$B_{\mathbf{m}} \sim \mathcal{N}(\bar{B}, \Sigma(\mathbf{m}))$$

- centered at prior value \bar{B} for any minipublic
- what varies with the minipublic is the **minipublic informativeness** $\Sigma(\mathbf{m})$
- $B_{\mathbf{m}}$ is more spread out \Rightarrow minipublic is more informative

Minipublic informativeness

Let \mathcal{M} be the set of all finite selections from $[0, 1]$

$$\mathcal{M} := \bigcup_{n \geq 0} \mathcal{M}_n$$

Assumption

The minipublic informativeness given by the function $\Sigma : \mathcal{M} \rightarrow [0, \sigma^2]$ satisfies the following properties:

- (i) $\Sigma(\emptyset) = 0$;
- (ii) for any $\mathbf{m} \subsetneq \mathbf{m}'$, $\Sigma(\mathbf{m}) < \Sigma(\mathbf{m}')$;
- (iii) Σ is continuous at any $\mathbf{m} \in \mathcal{M} \setminus \emptyset$.

Payoffs

Both the policymaker and minipublic citizens care about the value of the policy B (“the common good”)

- Each minipublic citizen obtains B from adoption and 0 otherwise
- Policymaker obtains $(B - c)$ from adoption and 0 otherwise, where

$$c \sim \mathcal{N}(0, \tau^2)$$

- τ^2 captures the extent of **political uncertainty**
- c is the **threshold of adoption** of the policymaker

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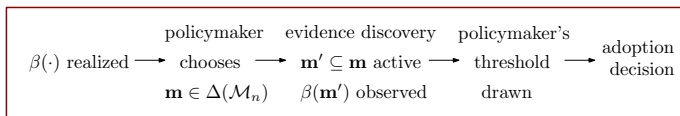
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Interpretation: c captures any wedge between the contribution of the policy to the public interest and to other idiosyncratic interests of the policymaker

- shift in priorities due to rare/unexpected events (e.g., pandemics)
- budgetary pressures / bureaucratic friction
- impact on key stakeholders: lobbyists, advocacy groups, party supporters
- implications for policymaker’s political legacy

Actions and timing

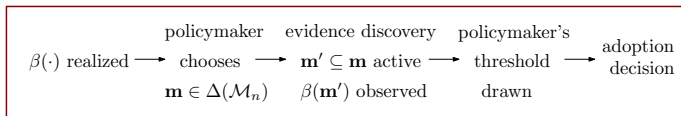


The game proceeds in 3 stages:

1. Minipublic choice

- policymaker chooses a lottery over minipublics $\Delta(\mathcal{M}_n)$
- each $i \in \mathbf{m}$ observes the entire \mathbf{m}

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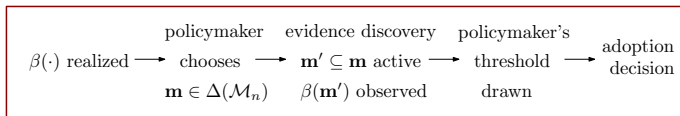
1. Minipublic choice

- policymaker chooses a lottery over minipublics $\Delta(\mathcal{M}_n)$
- each $i \in \mathbf{m}$ observes the entire \mathbf{m}

2. Evidence discovery

- each $i \in \mathbf{m}$ can **costlessly and publicly discover** $\beta(i)$
- all evidence discovery in \mathbf{m} is **simultaneous**
- if $i \in \mathbf{m}$ does (not) discover $\beta(i)$, we say i is **active (passive)**

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3. Policy adoption

- policymaker observes **all discovered evidence** and **the adoption threshold**
- she decides between the policy and the status quo

1. **Microcosm** of the larger citizenry
 - informative about population-wide effects of the policy
2. **Targeted recruitment** of minipublic citizens
 - not elected or self-selected into minipublic
3. **Advisory** role, no decisional authority
 - uncertainty about minipublic's eventual impact on policymaking
4. Mechanism for **producing public evidence** about novel policies
 - rather than aggregating existing private information

1. **Information design with multiple senders:** Gentzkow and Kamenica (2016, 2017), Li and Norman (2018), Koessler, Laclau and Tomala (2018), Boleslavsky and Cotton (2018), Au and Kawai (2019, 2020)
Selective learning among multiple correlated attributes: Liang, Mu and Syrgkanis (2021), Bardhi (2022), Bergemann, Bonatti and Gan (2020)
2. **Optimal composition of a team of experts:** Hong and Page (2001), Lamberson and Page (2012), Chade and Eeckhout (2018)
Collective evaluation: Gerardi and Yariv (2008), Moldovanu and Shi (2012), Name Correa and Yildirim (2020)
3. **Multi-dimensional learning and Gaussian processes:** Jovanovic and Rob (1990), Callander (2011), Callander and Clark (2017), Callander, Lambert and Matouschek (2018), Bardhi (2022), Carnehl and Schneider (2022)
4. **Minipublics:** Dahl (1989), Chambers (2003), Ferejohn (2008), Fishkin (2009), Warren and Gastil (2015), Kwiek (2020)

Baseline model

Policymaker's problem

Optimal minipublic

Minipublic size

Minipublic composition

Comparative statics

Discussion

Fix a minipublic \mathbf{m} + evidence discovery strategy profile $(\delta_i)_{i \in \mathbf{m}}$

⇒ lottery over **active minipublics** $\hat{\mathbf{m}} \subseteq \mathbf{m}$

⇒ policymaker observes only the realized outcomes $\beta(\hat{\mathbf{m}})$

Key observation: All players' expected payoffs depend on $\hat{\mathbf{m}}$ only through $\Sigma(\hat{\mathbf{m}})$

Policymaker's payoff

Policymaker adopts the policy if and only if $B_{\hat{\mathbf{m}}} \geq c$

The expected payoff from adoption is

$$V_P(\Sigma(\hat{\mathbf{m}})) := \int_{-\infty}^{+\infty} \Pr [B_{\hat{\mathbf{m}}} \geq c] \mathbb{E} [B_{\hat{\mathbf{m}}} - c | B_{\hat{\mathbf{m}}} \geq c] d\Phi\left(\frac{c}{\tau}\right)$$

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Policy maker's payoff

Policy maker adopts the policy if and only if $B_{\hat{m}} \geq c$

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Lemma

The policymaker's expected payoff is strictly increasing in Σ .

- Policy maker's problem is to best predict whether $B \geq c$
- For any c , higher $\Sigma \Rightarrow$ better prediction \Rightarrow more accurate decision
- A more informative minipublic preferred before c is realized as well
- Hence, policymaker **maximizes informativeness**

Citizen's payoff

All citizens have the same expected payoff from informativeness Σ :

$$V_C(\Sigma(\hat{\mathbf{m}})) := \int_{-\infty}^{+\infty} \Pr [B_{\hat{\mathbf{m}}} - c \geq 0] \mathbb{E} [B_{\hat{\mathbf{m}}} | B_{\hat{\mathbf{m}}} - c \geq 0] d\Phi\left(\frac{c}{\tau}\right)$$

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Lemma

The citizen's expected payoff is strictly quasiconvex in Σ , with a minimum at

$$\underline{\Sigma} = \max\left\{0, \frac{1}{2}\left(\sqrt{\tau^4 + 4\bar{B}^2\tau^2} - 3\tau^2\right)\right\}.$$

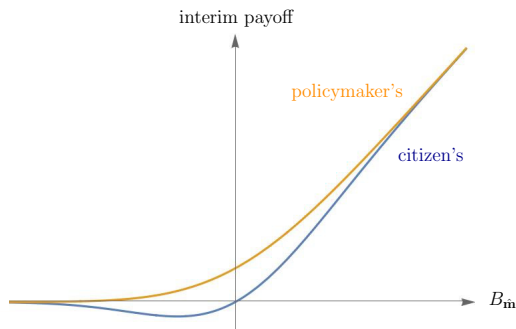
- If $\underline{\Sigma} = 0$ no conflict between policymaker and citizens
- But citizen's payoff need not be increasing in informativeness
 \Rightarrow Citizen does not necessarily prefer contributing to informativeness

Expected misalignment for any post-minipublic value

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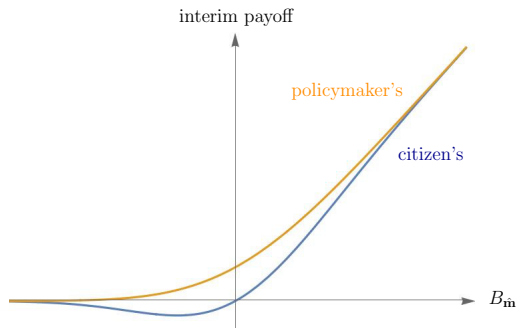
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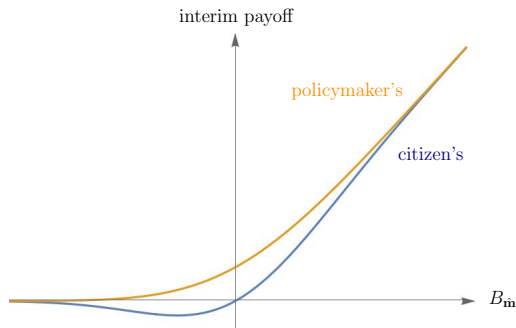
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- Policymaker's payoff is increasing and convex at any $B_{\hat{m}}$
- Citizen's payoff is U-shaped in $B_{\hat{m}}$, convex for $B_{\hat{m}}$ close to zero and concave for $B_{\hat{m}}$ far from zero

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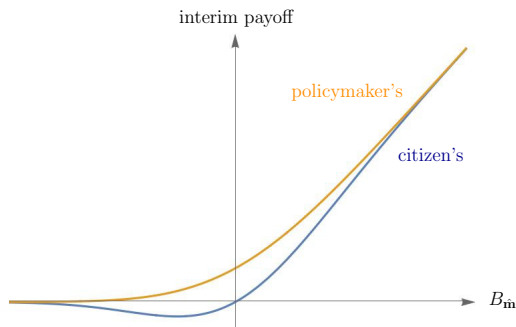
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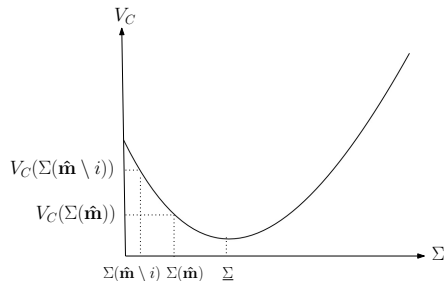
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- Expected misalignment is highest for $B_{\hat{m}}$ close to zero
- When does the citizen prefer a mean-preserving spread around \bar{B} ?

Citizen's payoff



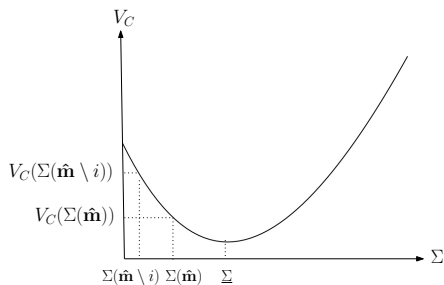
- **active informativeness** of citizen i :
 $\Sigma(\hat{\mathbf{m}})$
- **passive informativeness** of citizen i :
 $\Sigma(\hat{\mathbf{m}} \setminus i)$
- **marginal informativeness** of citizen i :

$$M_i(\mathbf{m}) = \Sigma(\hat{\mathbf{m}}) - \Sigma(\hat{\mathbf{m}} \setminus i)$$

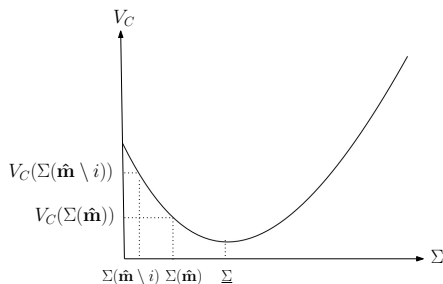
Evidence discovery (ED) constraint fixing $\hat{\mathbf{m}}$:

$$V_C(\Sigma(\hat{\mathbf{m}})) \geq V_C(\Sigma(\hat{\mathbf{m}} \setminus i))$$

Curse of too little information

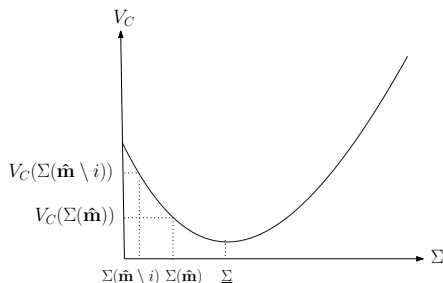


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1. negative marginal value of information at $\Sigma = 0$
 - that is, $\underline{\Sigma}$ must be to the right of zero
 - a small amount of information harms the citizen
2. sufficiently uninformative minipublic
 - both $\Sigma(\hat{\mathbf{m}} \setminus i)$ and $\Sigma(\hat{\mathbf{m}})$ must be sufficiently small relative to $\underline{\Sigma}$

Equilibrium selection

We focus on **policymaker-preferred** Perfect Bayesian equilibria.

Lemma

In the class of policymaker-preferred Perfect Bayesian equilibria, it is without loss to restrict attention to

- *no randomization over minipublics,*
- *pure strategies at the evidence discovery stage (i.e., each citizen in minipublic is active or passive with probability one),*
- *no passive citizens in the minipublic.*

Policymaker's minipublic choice problem

$$\max_{\mathbf{m} \in \mathcal{M}_n} \Sigma(\mathbf{m}) \quad (\text{P})$$

$$\text{s.t. } V_C(\Sigma(\mathbf{m})) \geq V_C(\Sigma(\mathbf{m} \setminus i)) \quad \forall i \in \mathbf{m}. \quad (\text{ED})$$

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- Policymaker's unconstrained problem: maximizing informativeness
- Set of first-best minipublics \mathcal{M}_n^f
- Any first-best minipublic consists of exactly n citizens
- Normative benchmark for minipublic diversity absent strategic considerations

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No distortion in minipublic size

Does policymaker ever sample fewer citizens than what capacity allows?

Proposition (Optimal minipublic size)

Given capacity n , the optimal minipublic either is empty or consists of exactly n active citizens.

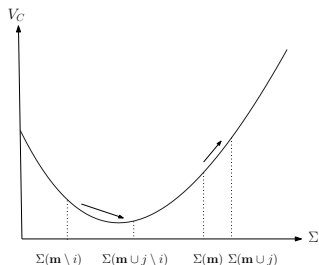
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Given capacity n , the optimal minipublic either is empty or consists of exactly n active citizens.

If \mathbf{m} has $n' < n$ citizens, adding a new citizen $j \notin \mathbf{m}$ relaxes all (ED) while improving overall informativeness



⇒ If first-best not feasible, then either **distorted minipublic composition with n citizens** or **no minipublic**

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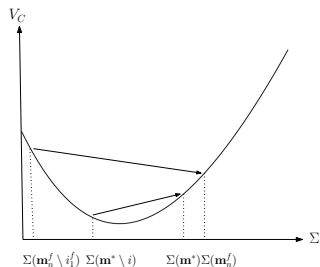
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Reduced marginal informativeness

Passive citizens have excessively high marginal informativeness

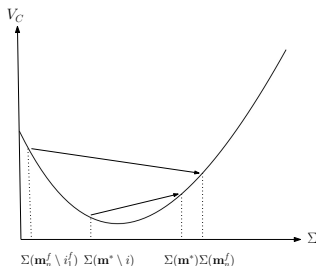
⇒ If first-best not feasible, marginal info ↘ and passive info ↗



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Proposition (Reduced marginal informativeness)

If an optimal minipublic m^ is neither empty nor a first-best one, then the marginal informativeness for any $i \in m^*$ is strictly lower than the highest marginal informativeness in any first-best minipublic.*

The “largest piece of novel evidence” is less novel than in the first-best minipublic

We impose additional structure on the nature of local evidence

- (1) The value of the policy corresponds to the policy's average local impact:

$$B := \int_0^1 \beta(i) di$$

Ornstein-Uhlenbeck correlation of local evidence

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Assumption (Distribution of the local impact mapping)

The local impact mapping β is drawn from the set of sample paths of an Ornstein-Uhlenbeck process on $[0, 1]$ where for every $i, j \in [0, 1]$

1. $\beta(i) \sim \mathcal{N}(\bar{\beta}(i), 1)$
2. *correlation between $\beta(i)$ and $\beta(j)$ is given by $e^{-|i-j|/\ell}$ with $\ell \in (0, +\infty)$.*

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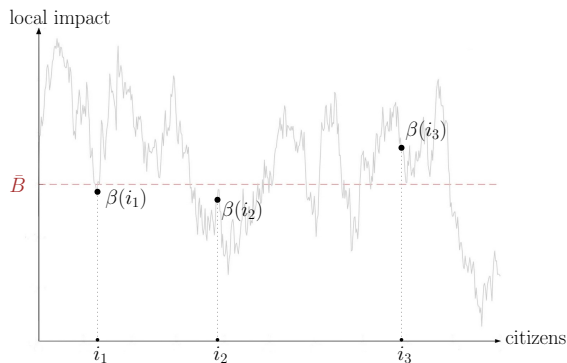
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2. correlation between $\beta(i)$ and $\beta(j)$ is given by $e^{-|i-j|/\ell}$ with $\ell \in (0, +\infty)$.

ℓ captures the degree of *homogeneity* among citizens

- $\ell \rightarrow +\infty$: almost perfectly correlated outcomes (very **homogeneous**)
- $\ell \rightarrow 0$: almost independent outcomes (very **heterogeneous**)

Ornstein-Uhlenbeck correlation of local evidence



This structure implies a tractable form for $\Sigma(\cdot)$

⇒ precise characterization of the composition of the optimal minipublic

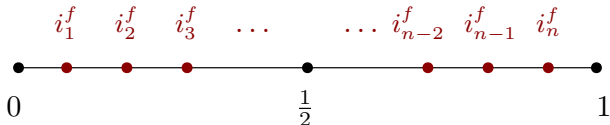
⇒ implications for demographic diversity

First-best minipublic

Corollary (Proposition 3.5 in Bardhi (2022))

For any n , there exists a unique first-best minipublic \mathbf{m}_n^f that satisfies the following:

- (i) it is symmetric about the median citizen: $i_k^f = 1 - i_{n-k+1}^f$ for every k ;
- (ii) the distance between adjacent citizens Δ_n^f is constant: $i_k^f - i_{k-1}^f = \Delta_n^f$ for all $k \in \{2, \dots, n\}$;
- (iii) the distance Δ_n^f is such that the post-minipublic value $B_{\mathbf{m}_n^f}$ weighs equally the realizations $\beta(i_1^f), \dots, \beta(i_n^f)$.



In this first-best minipublic, peripheral citizens i_1^f and i_n^f have the highest marginal informativeness

Small minipublics

- In order to reduce the marginal informativeness of peripheral citizens, their neighbors must be brought closer

$$i_2^* < i_2^f, \quad i_{n-1}^* > i_{n-1}^f$$

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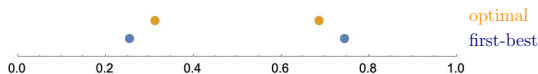


Figure 2: $n = 2$

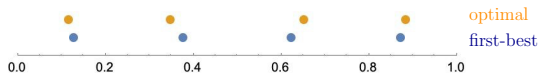


Figure 3: $n = 4$

General characterization

For $n \geq 5$, only two patterns of distortions are possible:

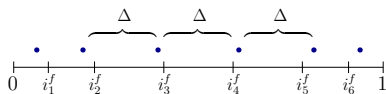


Figure 4: Δ -equidistant

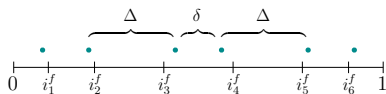


Figure 5: (δ, Δ) -alternating

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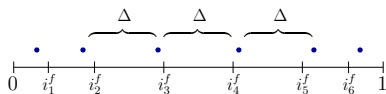


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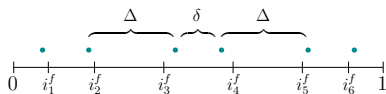


Figure 5: (δ, Δ) -alternating

Of these two patterns, the equidistant one is predominant

- The alternating pattern is **suboptimal** if an equidistant minipublic is **feasible**
- The alternating one can arise for **at most one capacity**

Proposition (Distortions in the optimal minipublic)

Let $n \geq 5$. Any optimal minipublic $\mathbf{m}^* = \{i_1^*, \dots, i_n^*\} \notin \{\emptyset, \mathbf{m}_n^f\}$ satisfies the following properties:

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Computationally, this simplifies the optimization problem

- from n variables (citizens) ...
- to at most two variables (adjacent distances) ...
- and at most two binding (ED) constraints.

Representativeness and **diversity**: desirable features in minipublic design (Flanigan et al. (2021), Steel et al. (2020), Fishkin (2011), Brown (2006))

Steel et al. (2020): *“both of these concepts can be interpreted in more than one way, and furthermore the two can lead in different directions”*

Demographic diversity \equiv distance between adjacent demographics

- characterization of \mathbf{m}^* has precise implications for demographic diversity
- equidistant \mathbf{m}^* strictly less diverse than \mathbf{m}^f

But to what extent is the optimal minipublic representative of the citizenry?

Demographic diversity and representativeness

We compare representativeness of the \mathbf{m}^* and \mathbf{m}^f according to three natural representativeness measures:

1. random sampling of minipublic citizens (Fishkin, 2009)
 - demographic distance from the expected random sample
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3. Ψ -representativeness

$$\Psi(\mathbf{m}) := \int_0^1 (1 - \text{var} [\beta(i) | \beta(\mathbf{m})]) di$$

- a Rawlsian criterion: how well the local impact of the minipublic citizens predicts the local impact of any randomly drawn citizen
- the ranking of the representativeness of \mathbf{m}^* and \mathbf{m}^f can go either way

Baseline model

Policy maker's problem

Optimal minipublic

Minipublic size

Minipublic composition

Comparative statics

Discussion

Greater political uncertainty \Rightarrow harder to motivate evidence discovery?

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Political uncertainty has a **non-monotonic** effect on the optimal minipublic

- Curse of too little information disappears for either high or low τ^2

Dependence on political uncertainty

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Political uncertainty has a **non-monotonic** effect on the optimal minipublic

- Curse of too little information disappears for either high or low τ^2

Proposition (No distortions under high or low political uncertainty)

Fix all parameters other than τ^2 . There exist cutoffs $0 < \underline{\tau}^2 \leq \bar{\tau}^2 < \infty$ such that $\mathbf{m}^* = \mathbf{m}_n^f$ if political uncertainty is either

- sufficiently low (i.e., $\tau^2 \leq \underline{\tau}^2$), or
- sufficiently high (i.e., $\tau^2 \geq \bar{\tau}^2$).

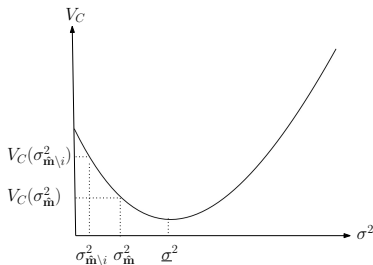
\Rightarrow **What hampers evidence is moderate, rather than high, uncertainty**

Dependence on political uncertainty

τ^2 determines the V_C -minimizing level of informativeness $\underline{\sigma}^2$

$$\underline{\sigma}^2 = \max \left\{ 0, \frac{1}{2} \left(\sqrt{\tau^4 + 4\bar{B}^2\tau^2} - 3\tau^2 \right) \right\}$$

- as $\tau^2 \rightarrow 0$ and as $\tau^2 \rightarrow +\infty$, informativeness $\underline{\sigma}^2 \rightarrow 0$
- V_C strictly increasing in informativeness (in the limit)
- any minipublic becomes active



However the economic intuition is different at each extreme...

Low uncertainty: $\tau^2 \rightarrow 0$

As political uncertainty vanishes

- policymaker prefers the same adoption decision as the citizens ex post
- expected misalignment vanishes for any post-minipublic value
- $V_C - V_P \rightarrow 0$

Dependence on political uncertainty

High uncertainty: $\tau^2 \rightarrow +\infty$

As political uncertainty becomes arbitrarily large

- policymaker's decision fully unpredictable
- probability of adoption $\rightarrow 1/2$
- expected misalignment unboundedly high for any post-minipublic value
- citizens cannot affect expected misalignment by being passive
- interim payoff strictly convex for any $B_m \in (-\sqrt{2}\tau, \sqrt{2}\tau)$

Moderate uncertainty

But...

when political uncertainty is **moderate**, citizen might find it worthwhile to remain passive because

1. ex post misalignment **sufficiently likely**
- +
2. citizen can **influence significantly** the likelihood of ex post misalignment

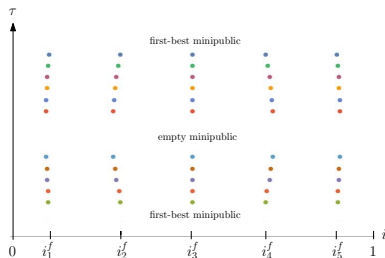
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Other comparative statics (in \bar{B} , n , and ℓ) in the paper

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- OECD (2020): *policy impact* and *representativeness* as two desiderata for minipublic design

policy impact: “the commissioning public authority should publicly commit to responding to or acting on participants’ recommendations”

representativeness: “the participants should be a microcosm of the general public”

- Our analysis sheds light on the interaction between these desiderata

No tension if political uncertainty either very high or very low

- CCC faced low political uncertainty when it was formed, as it was preceded by the Grand Débat National

But if uncertainty is greater, citizens might self-select out

- UK Climate Assembly (CAUK)
- Preceded by a general election:
 - “a change of Chairs and members of the six CAUK commissioning committees, with some of the newcomers less supportive of CAUK and the net zero target”
- Selection criteria suggestive of targeting greater diversity
 - oversampling of extreme education levels, oversampling of marginal groups, sampling based on climate change attitudes etc.

When impact of minipublic not guaranteed, representativeness might get sacrificed.

- Noisy evidence discovery
- Biased policymaker
- Uncertain thresholds for citizens
- Private evidence discovery
- Coordination within a minipublic
- Privately interested citizens
- Delegation of decisional authority

Thank you!